Timing System at KEK 8-GeV Linac

Kazuro Furukawa, Tsuyoshi Suwada, Norihiko Kamikubota, Masanori Satoh Electron/Positron Linac at KEK <URL:http://www-linac.kek.jp/>

The timing system of the KEK electron linac has been restructured for the KEKB project since a higher precision was required compared with the previous project. It provides precise timing signals for accelerator equipement such as guns, rf sources, beam instrumentation, etc. along the 600-m linac. The signals can be synchronized to one of three rings, KEKB, PF and PF-AR. The clock system consists of five synchronized frequencies to drive different rf systems. The main clock of the timing system is 571.2MHz, which is distributed through a coaxial cable overwrapped with timing pulses. The delayed signals for over 100 devices are generated at 15 timing stations along the linac. Gate pulses are also distributed to enable intermittent measurement, etc. Timing signals are controlled through VME and CAMAC with the linac standard control architecture. The delay step of the timing signals is 1.75 ns and the precision is better than 5 ps depending on the location. It enabled stable long-term operation of the linac and also the recent "two bunch in a pulse" operation with its precise controls.

Introduction

Experiment Efficiency for B-Factory

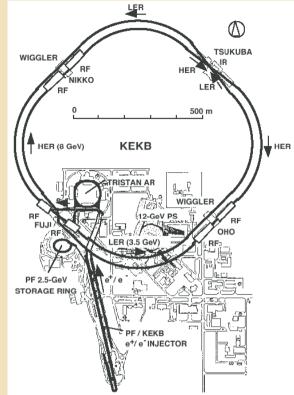
- **KEKB Electron Positron Asymmetric Collider**
- ⇒ Stable Operation of Linac
 - **Further Improvement**
 - with 2-bunch and Continuous Injection

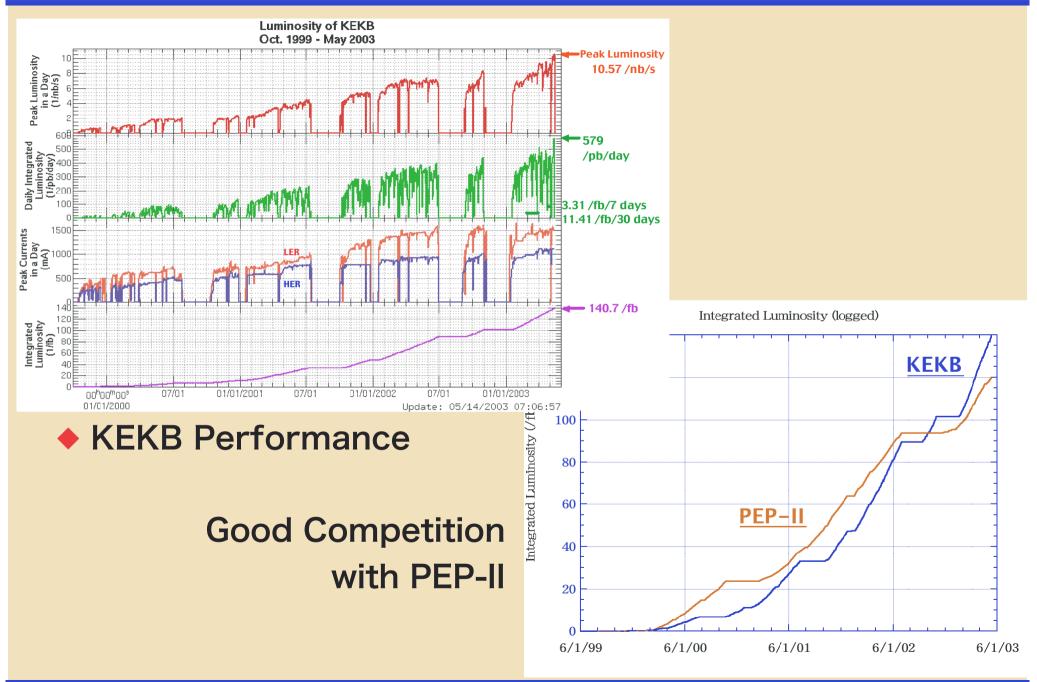
Timing System

High Precision Injection Timing (<30ps,SingleBunch) Timing Controls for SLED and 2-bunch Inj. More than 100 Timing Devices along 600m

Frequent Beam Mode Switch (~50 Times a Day)

- KEKB e- 8 GeV 1.2nC Single Bunch
- KEKB e+, 3.5 GeV 0.64nC Single Bunch with/without 2 Bunch Injection (Primary e– 10nC)
- PF e- 2.5 GeV 0.3nC Multibunch
- PF-AR e- 2.5/3.0 GeV 0.3nC Multibunch





Timing System of Injector Linac

Timing Delivery for

- Beam from Electron Gun
- Pulsed Microwave Generation, Envelope, SLED Energy Doubler
- Timing for Beam Instrumentation
- Injection Timing, Kicker/Septum Trigger

Components Provide

- Generation of Base Clocks
- Distribution of Timing Signal
- Generation of Hundreds of Delayed Signals at 15 Timing Stations

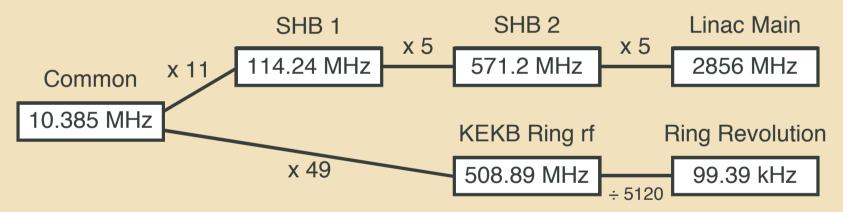
• with Good Collaboration between Several Equipment Groups

Generation of Base Clocks

 (300ps Jitter was Allowed in Previous Project TRISTAN Asynchronous rf between Linac and Ring)

In KEKB, Single Bunch Beam with Jitter <30ps Required</p>

⇒ Need Integer Relation between rf Frequencies



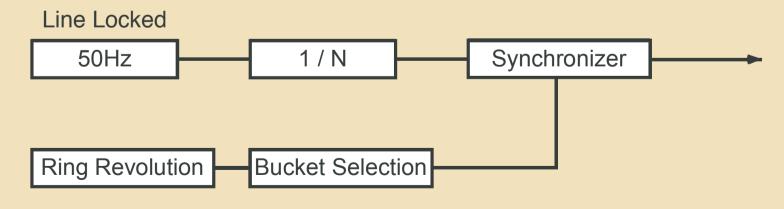
 All rf and Timings should be Based on Common Fundamental Frequency 10.385 MHz
 Freq. Multiplier/Divider was Developed for these rfs

Beam Timing

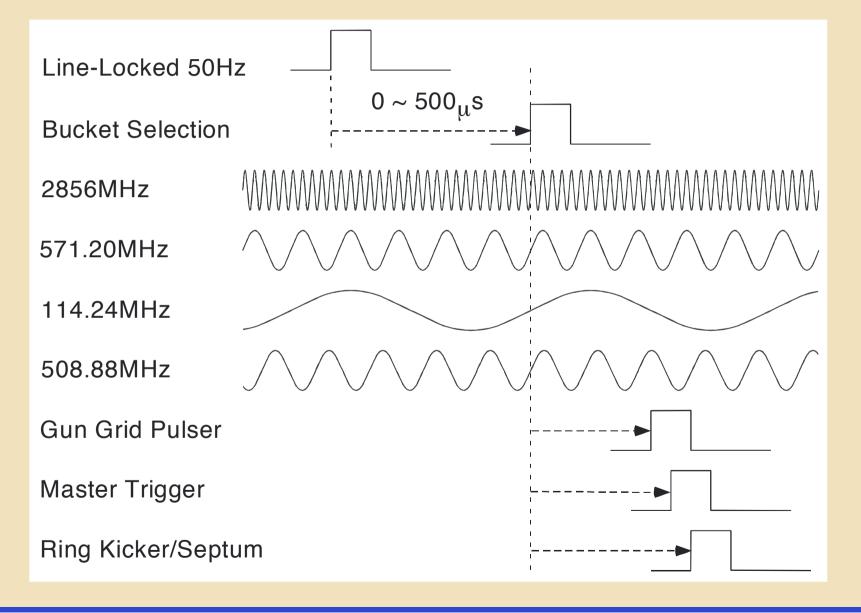
Beam Timing is Synchronized to Both
 Power Line Frequency (50Hz) (for Noise Elimination)
 Revolution Frequency of Each Ring (with Bucket Selection)

For Bucket Selection in KEKB Injection
 Synchronizing Also to Common Freq. (10.39MHz)
 (With Maximum Delay of 0.5ms for 5120 Buckets)

Can Reduce to 1/N Rate



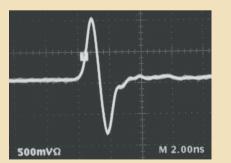
Simplified Timing Chart



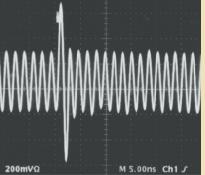
Distribution of Timing and Clock

- Required High-precision Timing at each Equipment Different Requirement depending on Equipment Precision <10ps, 1ns, 10ns; Step ~1ns
- Distribute Clock (571.2MHz) for Delay Counters
- Over the Same Cable with High Band-width
- 15 Timing Stations

Mono-Pulse Beam Timing

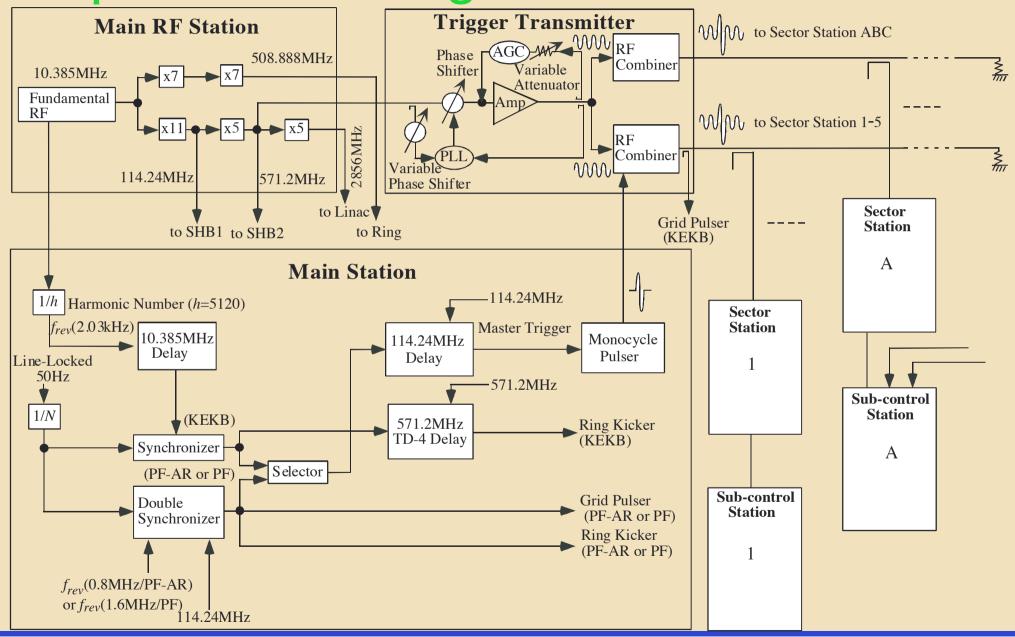


Overwrap with Clock (571.2MHz)



Re-Generate Timing and Clock at each Station

Simplified Block Diagram



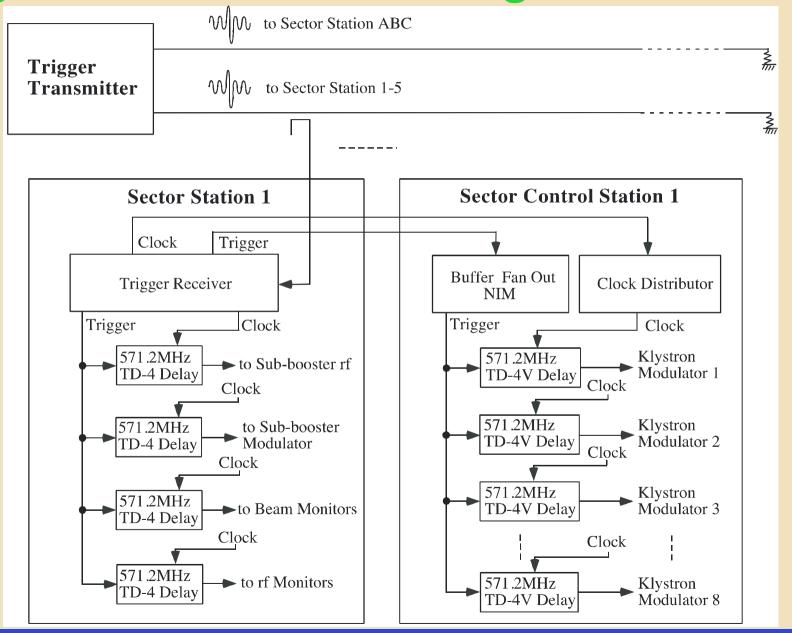
Timing Station

- Main Station and 15 Sub-Stations
- Main Station Generates Base Signals and Distributes them
- Sub-Stations Generate Delayed Timings
- TimingDelay4 (TD4) ECL 16bit Counter Delay (Max 114μs)

Sub-Stations

Station	Beam Station	Primary Sub-Station	Secondary Sub-Station
Number Receiver	1 TD4R	9 Trigger Receiver	5 -
Delay	TD4R	TD4	TD4V
Field Bus	RS232C	CAMAC	VME
Equipment	Beam Gun	Low-level rf Beam Monitor	Modulator

Timing Transmission and Re-generation



Pulsed Microwave Timing

 Low-level Microwave Timing Pulse Envelope, SLED (rf Compressor) Phase Flip 57 μs Delayed Pulse for Stand-by rf Units 8 Sub-stations, 32 Timing Signals (~1ns stability)

 High-power Klystron Modulator Timing High-voltage Pulse Timing 6 Sub-stations, 59 Timing Signals



Timing for Beam Instrumentations

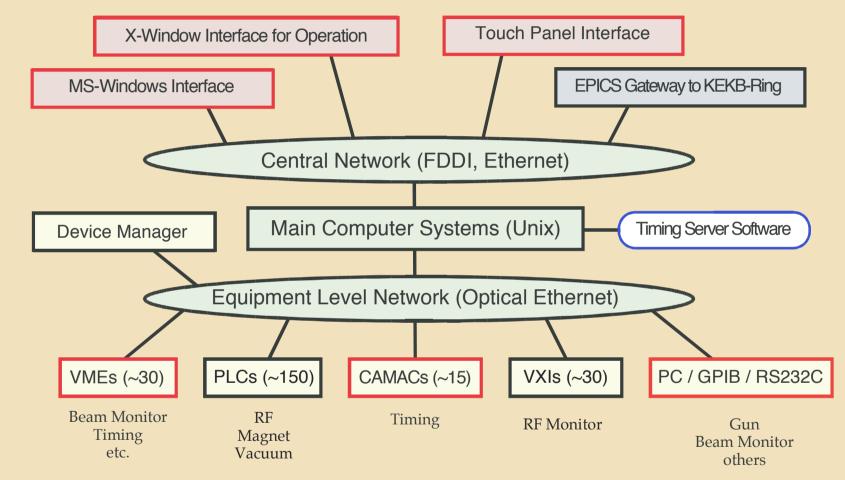
Streak Camera
 Precision Much Better than 10ps
 4 Locations

Beam Position Monitors
 Precision Better than 1ns (Software Finds Real Peak Locations)
 19 Locations, 90 BPM's

Beam Wire Scanners
 Precision Better than 1ns
 2Locations, 14 Scanners

 Source and Beam-Induced Microwave Monitors Precision Better than 1ns 8 Locations, 30 Monitor Stations

Control System



Red and Blue Boxes are Timing System Related
 Multi-layer Software Hides Hardware Differences

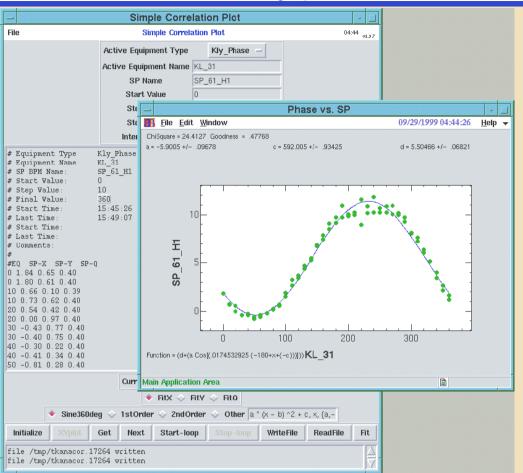
Timing System at KEK 8-GeV Linac

General Operation Tools can be Used with Timings

 Active Correlation Plot enables Automated Parameter Optimization

> Passive Correlation Plots are also Used to Find Multi-Parameter Correlations

		Linac Parameters		
File		Linac Parameters 08:52 08:52	481	
$ ightarrow$ All \diamondsuit ABC Sect \diamondsuit 1-5 (Main) Sect $ ightarrow$ UserSaved \diamondsuit Periodical \diamondsuit LastSaved				
🛇 All 🗇 RF-Phase 💠 Kly-Es 🔹 Magnet 💠 Trig-Delay 💠 Acc-Mode				
List recent	List all	Sector selective load Device selective load		
data257.all	Sun Sep 26	5 00:26:58 1999 e+ tuning w/o ECS	\square	
data256.all	Sat Sep 25	5 22:55:22 1999 temporary		
data255.all	Sat Sep 25	5 20:14:53 1999 temporary		
data254.all	Sat Sep 25	5 12:58:23 1999 e+ tuning w/o BCS		
data253.all	Sat Sep 25	5 01:07:31 1999 e+ tuning w/o BCS		
lastOkbe.all	Fri Sep 24	16:25:38 1999		
lastOkbp.all		4 10:48:00 1999		
data252.all	1	<pre>1 01:34:16 1999 10nC after orbit correction A,B =</pre>		
data251.all	1	3 20:18:47 1999 8nC after orbit correction A-1 se		
last1kbe.all	1	3 10:23:55 1999		
data250.all		2 23:00:39 1999 PFOptics after injector well tuni		
data249.all		2 11:52:31 1999 PFOptics without set of 5 sector		
data248.all		L 23:53:16 1999 0.6nC up to 5sector		
data247.all		23:44:18 1999 0.6nC up to 5sector		
data246.all	Tue Sep 21	15:59:33 1999 0.4nC before J-ARC matching	17	
$\triangleleft _$				
Show	Qui	ckLoad Load Save Diff		



 Equipment Parameter Save-Load Panel Has Many Optional Features

Past Troubles

Ethernet-CAMAC Driver Software (Hytec ECC)
 Did not work well under Multi-server Multi-client Env.
 Much Work-around Software was Written

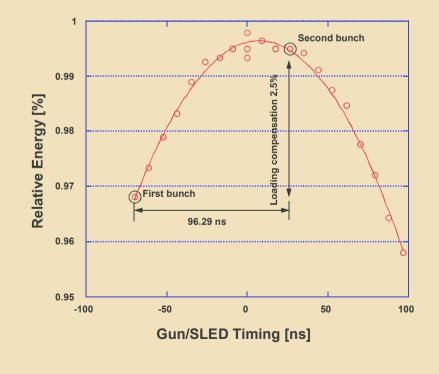
 Very Low-rate Output Failure with TD4/TD4V
 Comparator Chips for Input Discrim. and Output Width Stop Output Signals for just 200ms
 Rate was less than Once in 2 weeks
 All Comparators were Replaced

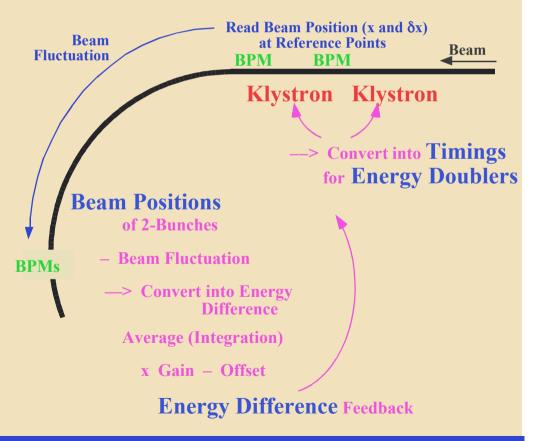
Bunch Energy Difference in 2-bunch Mode

Controls of Energy Difference with rf/SLED Timings

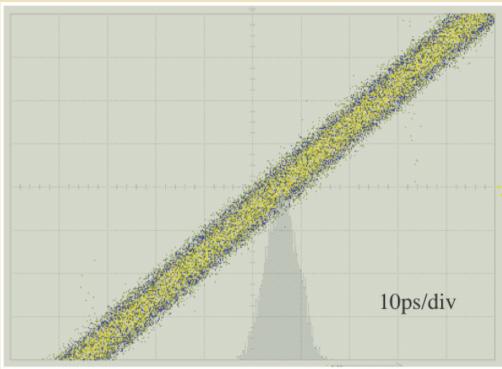
Energy Difference is Dependent on Bunch Current (Primary e- 10nC、Secondary e+ 1nC)

Simple Stabilization Loop



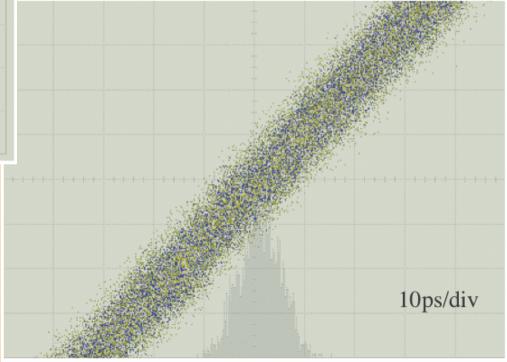


Jitter Evaluation



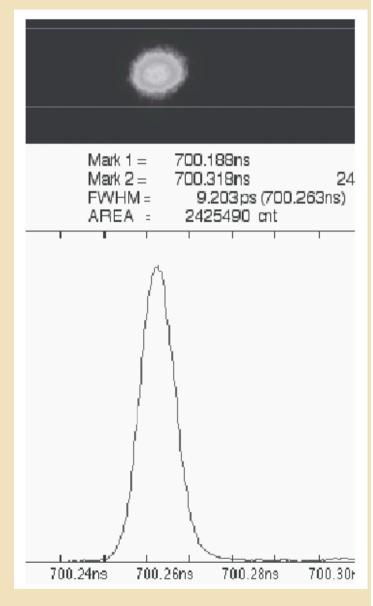
Single TD4 <3ps rms

Turn Around Through Sector-5 ~400m x 2 <4ps rms



Conclusion and Future

- Timing System Works as Expected Achieved Satisfactory Precision Flexible Controls of >100 Delays
- Performance of Timing System Based on Beam Width Meas. Far Better than 10ps (~3ps)
- Surveillance System
 Clock Phase Monitor Oscilloscope
 TD4 Monitor with TDC
- Improvement of Beam Operation 50Hz Instrumentations for Fast Beam Feedback etc.
 Intermittent Beam Monitoring Even During Continuous Injection



Thank you ...